

Teko: A Package for Multiphysics Preconditioners A Trilinos User Talk

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Eric C. Cyr Sandia National Laboratories







Outline

- 1. What is Teko?
- 2. Design Requirements and Overview
- 3. Using Thyra
- 4. Using Stratimikos
- 5. Thoughts on Trilinos
- 6. Summary



What is Teko?

- Teko means "Fuse (v)" in Greek
- Facilitates implementing "block" preconditioners
- Target applications are multiphysics systems
- Similar capabilities exist in Meros
 - Primarily focuses on Navier-Stokes solvers
 - Some utilized Thyra technology not actively supported



Current Teko Capabilities

Several preconditioners

Block 2x2 LU

Multiplicative

Block Gauss-Seidel

LSC (Navier-Stokes)

Block Jacobi

SIMPLE (Navier-Stokes)

Additive

- Thyra used for operator manipulation
- Able to use Trilinos solver/preconditioner capabilities for sub solves
- Blocking capability turns large system into blocked system



What is a block preconditioner?

MHD Equations are:

$$\frac{\partial(\rho\mathbf{u})}{\partial t} + \nabla \cdot (\rho\mathbf{u} \otimes \mathbf{u} + p\mathbb{I} + \mathbf{\Pi}) - \frac{1}{\mu_0} \nabla \times \mathbf{B} \times \mathbf{B} = 0$$
$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho\mathbf{u}) = 0$$
$$\frac{\partial \mathbf{B}}{\partial t} - \nabla \times (\mathbf{u} \times \mathbf{B}) + \nabla \times (\frac{\eta}{\mu_0} \nabla \times \mathbf{B}) = 0$$

Discretizing using an implicit time step gives

$$\begin{bmatrix} \begin{bmatrix} F & B^T \\ B & C \end{bmatrix} & \begin{bmatrix} Z \\ 0 \end{bmatrix} & \begin{bmatrix} u \\ p \\ b \end{bmatrix} = \begin{bmatrix} f \\ g \\ h \end{bmatrix}$$

Block Gauss-Seidel requires (approximate) inverses of

$$\begin{bmatrix} F & B^T \\ B & C \end{bmatrix}$$
 and D

What are the design requirements?

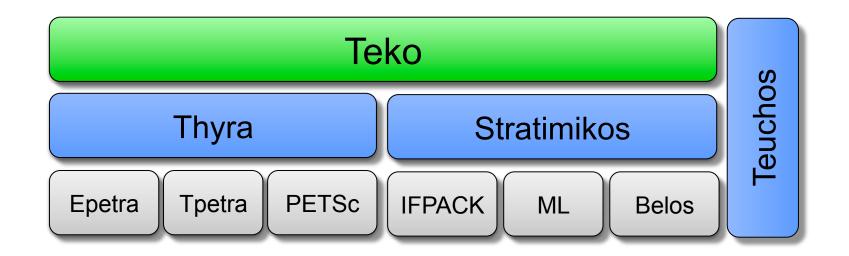
1. Preconditioners usable by Aztec and Belos solvers

- Reuse preconditioners in a recursive manner
- 2. Easily write a preconditioner
 - Blocking and manipulation capability:
 - Abstraction for reuse (I want to use Epetra, Tpetra or PETSc)
 - Specification of high-level algorithms easily
 - Inversion of blocks:
 - Use any preconditioner/solver in Trilinos
 - Easily specified by user

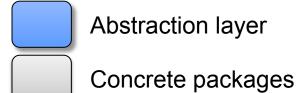




10,000 Feet: Teko Design



Color Code





Teko Example

Implement simple preconditioner (A) for A using Teko

$$A = \begin{bmatrix} A_{00} & A_{01} \\ A_{10} & A_{11} \end{bmatrix}, \ \tilde{A} = \begin{bmatrix} P & 0 \\ A_{10} & H \end{bmatrix}$$

where

$$P = A_{00} + \alpha A_{01}$$
 and $H = \text{diag}(A_{11})$

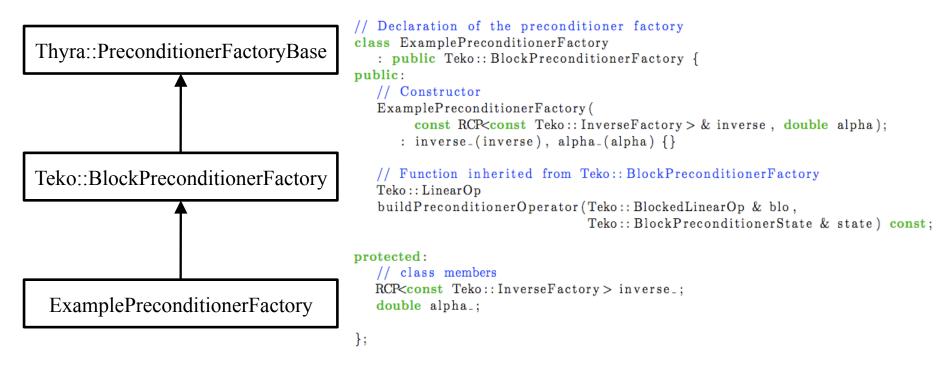
Notice preconditioner requires

$$\alpha$$
 and P^{-1}





Teko Example: Factory Definition



- Teko uses Thyra's preconditioner abstraction: use Aztec and Belos
- Teko simplifies implementing preconditioners by introducing an abstraction





Teko Example: Factory Implementation

```
// Use the factory to build the preconditioner
Teko::LinearOp ExamplePreconditionerFactory
:: buildPreconditionerOperator (Teko:: BlockedLinearOp & blockOp,
                              Teko:: BlockPreconditionerState & state) const
   int rows = Teko::blockRowCount(blockOp);
   int cols = Teko::blockColCount(blockOp);
   // extract subblocks
   const Teko::LinearOp A_00 = Teko::getBlock(0,0,blockOp);
   const Teko::LinearOp A_01 = Teko::getBlock(0,1,blockOp);
   const Teko::LinearOp A-10 = Teko::getBlock(1,0,blockOp);
   const Teko::LinearOp A-11 = Teko::getBlock(1,1,blockOp);
   // get inverse of diag(A11)
   const Teko::LinearOp invH = Teko::getInvDiagonalOp(A-11);
   // build 0.0 block in the preconditioner
   const Teko::LinearOp P
      = Teko:: explicitAdd(A-00, Teko:: scale(alpha-,A-01));
   const Teko::LinearOp invP = Teko::buildInverse(*inverse_,P);
   // build lower triangular inverse matrix
   Teko::BlockedLinearOp L = Teko::zeroBlockedOp(blockOp);
   Teko::setBlock(1,0,L,A_10);
   Teko::endBlockFill(L);
   std::vector<Teko::LinearOp> invDiag(2); // vector storing inverses
   invDiag[0] = invP;
   invDiag[1] = invH;
   Teko::LinearOp invTildeA
      = Teko::createBlockLowerTriInverseOp(L,invDiag);
   // return fully constructed preconditioner
   return invTildeA;
```

Recall:

$$A = \begin{bmatrix} A_{00} & A_{01} \\ A_{10} & A_{11} \end{bmatrix}$$

$$H = \operatorname{diag}(A_{11})$$

$$P = A_{00} + \alpha A_{01}$$

$$\tilde{A} = \begin{bmatrix} P & 0 \\ A_{10} & H \end{bmatrix}$$

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How is Thyra being used?

- All linear operator objects are based on Thrya
- Abstract Numerical Algorithms (ANA) idea permits expression of operations (+,-,*, etc...)
- Reuse of different linear algebra packages (in principle)
- Linear operator abstraction makes handling composite operators (relatively) transparent

$$\begin{bmatrix}
F & B^T \\
B & C
\end{bmatrix} & \begin{bmatrix}
Z \\
0
\end{bmatrix} \\
\begin{bmatrix}
Y & 0
\end{bmatrix} & D
\end{bmatrix}$$



How is Thyra being used?

- I've focused on small set of Thyra operators to use
 - Thrya::LinearOpBase **and** Thyra::PhysicallyBlockedLinearOpBase
 - Provide limited set of conversion functions
- In Teko RCPs are typedefed away

```
typedef Teuchos::RCP<Thyra::PhysicallyBlockedLinearOpBase> BlockedLinearOp;
typedef Teuchos::RCP<const Thyra::LinearOpBase> LinearOp;
typedef Teuchos::RCP<Thyra::LinearOpBase> ModifiableLinearOp;
```

- Tried to hide complexity of RCPs
- I think RCPs are great (users should get used to them)
- I may revert back





How is Thyra being used?

Some issues with Thyra

- What use cases does Thyra support?
 - Need diagonals
 - Need rows
 - Need explicit matrix products and sums
 - Is it more than a matrix-vector multiply?
- Complexity of interfaces and software architecture
 - Teko provides abstractions and wrapper functions
 - Depth of hierarchy can be overwhelming



What about inverses?

- Teko provides functionality for building inverses
 - Pair an "inverse factory" with linear operator

```
RCP<const Teko::InverseFactory> inverse = ...
Teko::LinearOp P = ...
const Teko::LinearOp invP = Teko::buildInverse(*inverse,P);
```

- Inverse factory abstraction makes building inverses easy
- How are inverse factories created and specified?
 - Inverse library object builds "inverse factories"
 - Library can be specified through an XML file



Building Inverse Libraries

- Inverse Libraries specified using parameter list
- Built on top of Stratimikos



Building Inverse Libraries

- Can build inverse library from XML list
- Uses Stratmikos to create solvers/preconditioners
- Inverse factory wraps Thyra::LOWSFactoryBase and

Thyra::PreconditionerFactoryBase

Inverse library builds sub-inverses as required





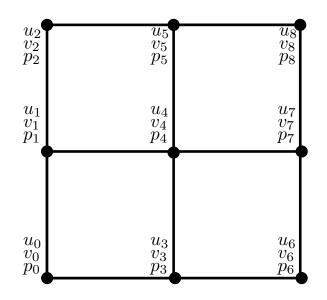
About Stratimikos

- Provides uniform interface for building Trilinos solvers/preconditioners
- Builds and applies inverse operator
- Distinguishes between a solver and a preconditioner
 - Inverse library hides this distinction
 - Value of this distinction in my case is debatable
- Building of multiple "inverses" of same type is tricky
 - Teko builds new Stratimikos object for each "inverse"





- Not all multiphysics matrices are (currently) blocked
- Teko provides capability for blocking a "strided" operator



$$\begin{bmatrix} A \end{bmatrix} \longrightarrow \begin{bmatrix} F & B^T \\ B & C \end{bmatrix}$$



General Trilinos Comments

I like CMake

- Built before with autotools
- Still don't like Makefile.export, good documentation is preferred
- Building Teko with CMake reasonably easy
- I dislike
 - "You can browse all of <package name> as a single doxygen collection. Warning: This is not the recommended way to learn about <package name> software."
- Experience with documentation is mixed
 - Documentation of parameter lists





Summary

- 1. Teko is package for multiphysics preconditioners
- 2. Sits on top of Thyra and Stratimikos
 - Thyra for Abstract Numerical Algorithms operations
 - Stratimikos for interfacing to Trilinos solver and preconditioner libraries
- 3. Teko will be available in "dev" branch soon (hopefully!)