

# Kokkos update: Memory Spaces, Execution Spaces, Execution Policies, Defaults, and C++11

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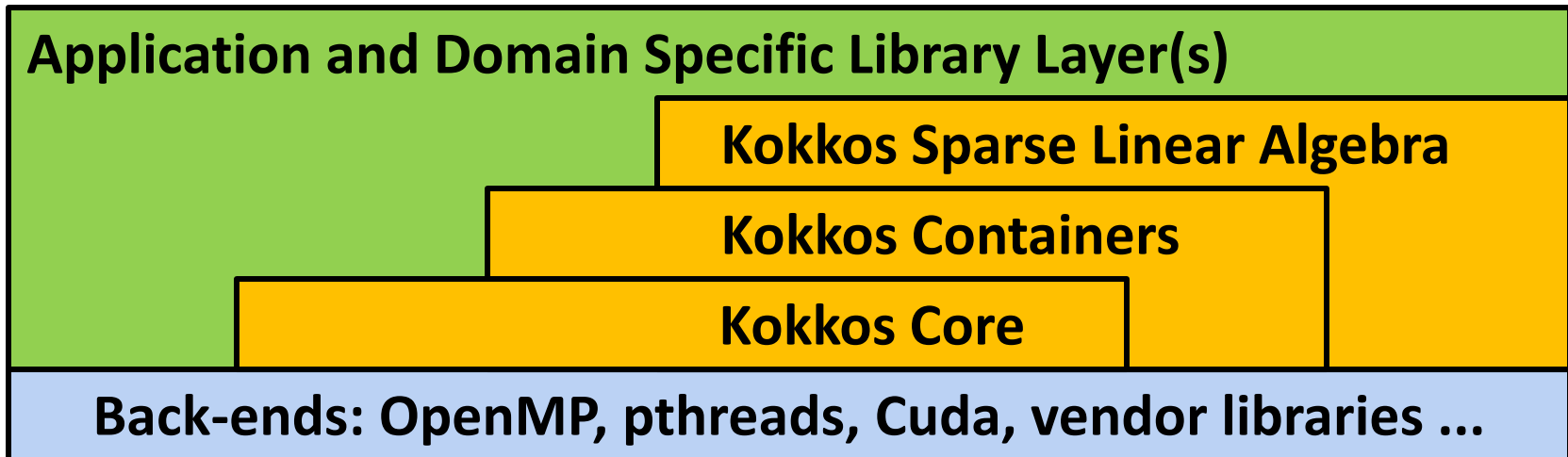


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# Kokkos: A Layered Collection of Libraries

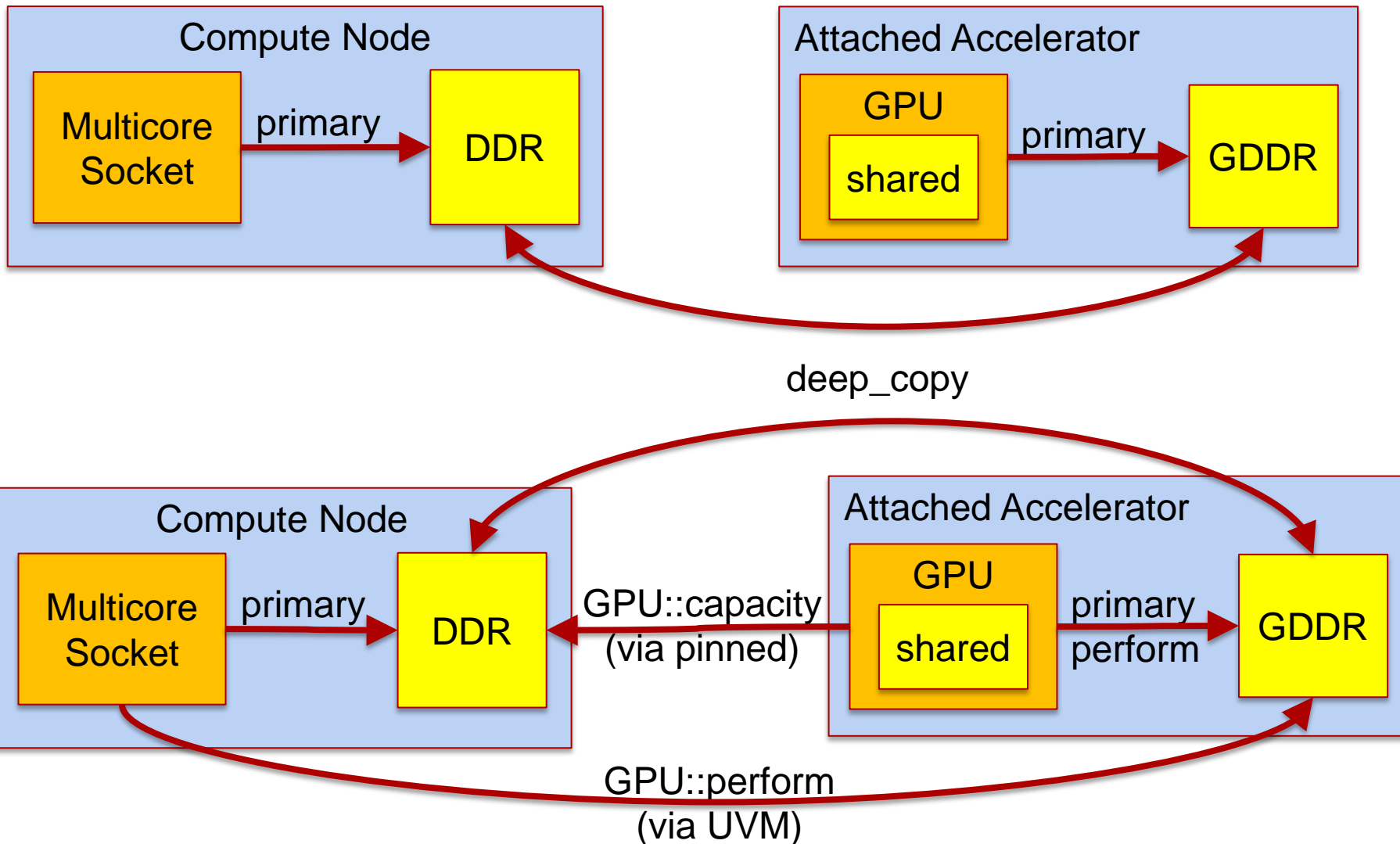


- C++1998 standard (everyone supports except IBM's xLC)
- C++2011 offers concise & convenient lambda syntax
  - Vendors catching up to C++11 language compliance
- **Concern: Can applications move to C++2011 ?**
  - Can just those applications moving to MPI + X also move to C++2011?
- C++2017 working on Kokkos Core -like thread parallel capability

# Kokkos: Spaces and Execution Policies

- **Execution Space** : where functions execute
    - Encapsulates hardware resources; e.g., cores, hyperthreads, vector units, ...
  - **Memory Space** : where data resides
    - AND what execution space can access that data
      - Also differentiated by access performance; e.g., latency & bandwidth
  - **Execution Policy** : how (and where) a function is executed
    - Identifies an execution space
    - E.g., data parallel range : concurrently call function(i) for i = 0 .. N-1
    - E.g., task parallel : concurrently call { tasks }
  - **Compose parallel pattern, execution policy, and functions**
    - Patterns: parallel\_for, parallel\_reduce, parallel\_scan, task\_parallel, ...
    - User's function is a C++ functor or C++11 lambda
- ```
parallel_for( Policy<Space>( ... ), Functor( ... ) );
```

# Examples of Execution and Memory Spaces



- **Execution Space *Instance***
  - Encapsulate (preferably allocable) hardware execution resources
  - Functions may execute concurrently on those resources
  - Degree of potential concurrency (cores, hyperthreads) determined at runtime
  - Number of execution space instances determined at runtime
- **Execution Space *Type* (e.g., CPU, Xeon Phi, GPU)**
  - Functions compiled to execute on a type of execution space
  - These types determined at configure/compile time
- **Host's Serial Space**
  - The main process and its functions execute in the host's Serial Space
  - One type, one instance, and is serial (potential concurrency == 1)
- **Execution Space *Default* : one instance of one type**
  - Configure/build with one type – it is the default
  - Initialize with one instance – it is the default
  - E.g., Kokkos::Threads, Kokkos::OpenMP, Kokkos::Cuda

- **Memory Space *Types*** (GDDR, DDR, NVRAM, Scratchpad)
  - The *type* of memory is defined with respect to an execution space type
  - Primary: (default) space with allocable memory (e.g., can malloc/free)
    - Performant : best performing space (e.g., GPU's GDDR)
    - Capacity : largest capacity space (e.g., DDR)
    - **Contemporary system: Primary == Performant == Capacity**
  - Scratch : non-allocable *and* maximum performance
  - Persistent : usage can persist between process executions (e.g., NVRAM)
- **Memory Space *Instance***
  - Accessibility and performance relationship with execution space
  - Directly addressable by functions in that execution space
  - Contiguous range of addresses
- **Memory Space *Default***
  - Default execution spaces' primary memory space

# Execution / Memory Space Relationship

- ( Execution Space , Memory Space , Memory Access Traits )
  - Accessibility : functions can/cannot access memory space
  - Readable / Writeable / Allocable
    - E.g., GPU performant memory using texture cache is read-only
  - Expectations for performance
  - Expectations for capacity
  
- Memory Access Traits (extension point)
  - examples: read-only, volatile/atomic, random, streaming, ...
  - Automatically convert between Kokkos::Views with same space but different memory access traits
  - Default is simple readable/writeable – no special traits

# Kokkos::View, Spaces, and Defaults

- `typedef View< ArrayType , Layout , Space , Traits > view_type ;`
  - Space is either memory space or execution space
    - Execution space has a default memory space
    - Memory space has a default execution space
  - Omit Traits : no special compile-time defined access traits
  - Omit Space : use default execution space
  - Omit Layout : use space's default layout
  - default everything: `View< ArrayType >`
  
- `View< double**[3][8] > : ArrayType == double**[3][8]`
  - Four dimensional array of value type 'double'
  - Dimensions are `[N][M][3][8]`
  - N and M are runtime defined dimensions



- **View<double\*\*[3][8], Space> a(spec,N,M);**
  - “Spec” for allocating memory or wrapping user-managed memory
  - Allocating memory, spec is
    - ViewAllocate( label = “” ), std::string(“label”), or “label”
    - ViewAllocateWithoutInitializing( label = “” )
    - Dimensions may have hidden padded for memory alignment
    - Label is only used for error and warning messages, need not be unique
    - Allocation, by default, initializes data via ‘parallel\_for’
  - Wrapping user-managed, spec is a pointer (no label)
    - Dimensions are taken as-is, are never padded for memory alignment
    - Trusting that the user’s memory spans the dimensions
- Data access: **a(i,j,k,l)**
  - Array layout deduced from ‘Space’ or ‘Layout’ template argument
  - Optional array bounds checking for debugging

# Kokkos::View Internal Reference Counting

- View semantics with internal reference counting
  - `View<double**[3][8],Space> b = a ; // SHALLOW copy`
  - Both 'b' and 'a' reference the same allocated memory
  - Memory deallocated when last referencing view is destroyed
- Wrapped user-managed memory is never reference counted
- `View< ... , Traits = MemoryUnmanaged >`
  - Do not reference count Views with this trait
  - Cannot allocate non-reference counted views
  - Use cases: temp subview of an allocated view, wrapping user's memory
  - Trusting that temporary subview does not outlive the allocated view
- 'Const-ness' of views and viewed data
  - `View<const double **[3][8],Space> c = a ; // OK, view to const array`
  - `const View<double**[3][8],Space> d = c ; // ERROR, non-const view of const`

# Deep Copy and “Mirror” Semantics

- `deep_copy( destination_view , source_view );`
  - Copy array data of ‘source\_view’ to array data of ‘destination\_view’
  - Kokkos policy: never hide an expensive deep copy operation
  - Only deep copy when explicitly instructed by the user
- Avoid expensive permutation of data due to different layouts
  - Mirror the dimensions and layout in Host’s memory space

```
typedef class View<...,Space> MyViewType ;  
MyViewType a(“a”,...);  
MyViewType::HostMirror a_h = create_mirror( a );  
deep_copy( a , a_h ); deep_copy( a_h , a );
```

- Avoid unnecessary deep-copy

```
MyViewType::HostMirror a_h = create_mirror_view( a );
```

- If Space (might be an execution space) uses Host memory space then ‘a\_h’ is simply a view of ‘a’ and `deep_copy` is a no-op

# Subview : View of a sub-array

```
SrcViewType src_view( ... );
```

```
DstViewType dst_view = subview<DstViewType>(src_view, ...args )
```

- *...args* : list of indices or ranges of indices
- **Challenging capability due to polymorphic array Layout**
  - **View's are strongly typed: View<ArrayType,Layout,Traits>**
  - **Compatibility constraints among DstViewType, SrcViewType, ...args**
    - 'const-ness' and other memory access traits
    - number of dimensions (rank of array)
    - runtime and compile-time dimensions
    - destination layout can accommodate when stride != dimension
  - **Performance of deep\_copy between subviews**
- **Using C++11 'auto' type would help address this challenge**
  - `auto dst_view = subview( src_view , ...args );`
  - Let implementation choose a compatible view type
  - **Caution: user will not have a priori knowledge of this type**

# Execution Policy : how functions are executed

```
pattern( Policy , Function );
```

- Execution policies (an extension point)
  - `RangePolicy<Space,ArgTag,IntegerType>( begin , end )`
  - `TeamPolicy<Space,ArgTag>( #teams , #thread/team )`
  - `TaskPolicy<...>` : experimental for Kokkos/Qthreads LDRD
  - `TeamVectorPolicy<...>` : experimental for hybrid thread-vector parallel
- Policies have defaults for all template arguments
- Function interface depends upon policy and pattern
  - `void operator()( ArgTag , Policy::member_type , ...args ) const ;`
  - `void operator()( Policy::member_type , ...args ) const ; // ArgTag == void`
  - `RangePolicy::member_type == IntegerType` iteration space
  - `TeamPolicy::member_type` has league-of-teams iteration space
  - `...args` depends upon pattern

# Execution Policy : how functions are executed

```
pattern( Policy , Function );
```

- Example with defaults and C++11 lambda (near-future capability)

```
parallel_for( N , KOKKOS_LAMBDA( int i ) { /* function body */ } );
```

- Integral N “policy” → RangePolicy<DefaultExecutionSpace,void,int>(0,N)
- Call function in parallel with  $i = 0 .. N-1$
- Example: parallel\_for( TeamPolicy< Space > , Functor );
  - void operator()( TeamPolicy<Space>::member\_type member ) const ;
  - league-of-teams-of-threads
    - member.league\_size() == number of teams
    - member.league\_rank() == which team is this within the league
    - member.team\_size() == number of threads within a team
    - member.team\_rank() == which thread is this within this team
  - Threads within a team are guaranteed concurrent, may not be synchronous
  - Intra-team collective operations: member.team\_barrier(), member.team\_reduce(...), member.team\_scan(...)
  - Intra-team shared scratch memory

# Parallel Patterns Function Interface

## ▪ `parallel_for( Policy , F )`

- `void F::operator()( Policy::member_type ) const ; // no ...args`

## ▪ `parallel_reduce( Policy , F )`

- `void F::operator()( Policy::member_type , value_type & update ) const ;`
- function contributes to reduction through 'update' argument

## ▪ `parallel_scan( Policy , F )`

`void F::operator()( Policy::member_type, value_type & update, bool final ) const ;`

- Parallel scan is a multi-pass operation
  - Each pass must contribute the exactly the same to 'update'
  - if ( final ) then 'update' is the parallel prefix sum value
- ## ▪ Inter-thread reduction functions (have defaults)
- `functor::init( value_type & update ) const ; // new( & update ) value_type();`
  - `functor::join( volatile value_type & update ,  
volatile const value_type & in ) const ; // update += in ;`

# Why ArgTag in Policy< Space , ArgTag >

- **Allow one functor to have multiple parallel work functions**
  - `parallel_for( RangePolicy<Space,TagA>(0,N) , my_functor );`
    - `calls: my_functor::operator()( const TagA & , int i );`
  - `parallel_for( RangePolicy<Space,TagB>(0,N) , my_functor );`
    - `calls: my_functor::operator()( const TagB & , int i );`
  - “ArgTag” because named member function cannot be used
- **Motivations**
  - Algorithm (class) with multiple parallel passes using the same data
  - Work functions can share member data and member functions
  - Common need in LAMMPS
    - allow LAMMPS to remove clunky “wrapper functor” pattern



# TeamVectorPolicy ← highly experimental !

- Three level hierarchy of parallelism: league, team, vector
- Thread of vector *lanes* (**experimental**)
  - Instructions applied lock-step in each lane
  - Vector collective operations: reduce, single
- Team of threads (current capability)
  - Each thread independently executes instructions in a shared function
  - Team collective operations: barrier, reduce, scan
  - Threads within a team share low-level resources
    - hyperthreads, L1 cache, transient scratch memory, ...
- League of teams of threads (current capability)
  - NO synchronization across teams
- Mapping onto GPU
  - Vector lane = GPU thread
  - Thread = GPU warp
  - Team = GPU block

# TeamVectorPolicy ← highly experimental !

## ▪ Example using C++11 lambdas

```
typedef TeamVectorPolicy<Space>::member_type member_type ;
void operator()( const member_type & member ) const
{
    // team collaboratively performs a parallel_for
    member.team_par_for( N , [&]( const int j ) { // j = 0..N-1
        double sum ;
        // each "thread" performs a reduction in a vector loop
        member.vector_par_reduce( M , [&]( const int k , double & val ){
            val += /* contribute from each lane */ ;
        }, sum );
        // One vector lane of the thread performs an operation
        member.vector_single([&]() { atomic_fetch_add(&global(),sum); }
    });
}
```

# Kokkos/Qthread LDRD: Task Parallelism

- **TaskPolicy< Space > and Future< type , Space >**

- Task policy object for a group of potentially concurrent tasks

```
TaskPolicy<> manager( ... ); // default Space
```

```
Future<type> fa = manager.spawn( functor_a ); // single-thread task
```

```
Future<type> fb = manager.spawn( functor_b ); // may be concurrent
```

- Tasks may be data parallel via data parallel pattern and policy

```
Future<> fc = manager.foreach(RangePolicy(0,N)).spawn( functor_c );
```

```
Future<type> fd = manager.reduce(TeamPolicy(N,M)).spawn( functor_d );
```

```
wait( tm ); // Host can wait for all tasks to complete
```

- Destruction of task manager object waits for concurrent tasks to complete

- **Task Manager : TaskPolicy< Space = Qthread >**

- Defines a scope for a collection of potentially concurrent tasks
- Have configuration options for task management and scheduling
- Manage resources for scheduling queue

# Kokkos/Qthread LDRD: Task Parallelism

- Tasks may have execution dependences
  - Start a task only after other tasks have completed

```
Future<> array_of_dep[ M ] = { /* futures for other tasks */ };
```
  - Single threaded task:

```
Future<> fx = manager.spawn( functor_x , array_of_dep , M );
```
  - Tasks and their dependences define a directed acyclic graph (dag)
- Challenge: A GPU task cannot ‘wait’ on dependences
  - An executing GPU task cannot be suspended – waiting blocks a processor
  - Other future light-weight core architecture may not be able to block as well
  - A task may spawn nested tasks and need to wait for their completion
  - Solution: ‘respawn’ the task with new dependences

```
manager.respawn( this , array_of_dep , M );  
return ; // ‘this’ returns to be called after new dependences complete
```

# Conclusion : Kokkos Strategy

- Evolves from “pure research” to “production growth”
  - Core abstractions and API stabilizes, as per today’s presentation
  - Move core of Kokkos from Trilinos to [github.com](https://github.com)
- Tutorial Examples and Mini-Applications using Kokkos
  - How to use Kokkos via examples
  - How to design and implement thread-scalable algorithms via mini-apps
- SON Website: [software.sandia.gov/drupal/kokkos](https://software.sandia.gov/drupal/kokkos)
- Tpetra and LAMMPS are migrating
- Long Term Strategy: C++17 or C++21 instead of Kokkos
  - ISO C++ Committee working to incorporate thread parallelism into standard
  - I am a voting member on this committee (several week-long mtgs/year)
  - Steer Kokkos *and* influence C++ standard → convergence