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EMPIRE: A Performance Portable Plasma Simulation Code

EMPIRC

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PRESENTED BY

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2 Motivation

- Sandia's foundation is science-based engineering, in which fundamental science, computer models, and unique experimental facilities come together so researchers can understand, predict, and verify weapon systems performance.
- EMPIRE (ElectroMagnetic Plasma In Realistic Environments) is a part of Sandia's nextgeneration plasma modeling and simulation capability.
 - Developed under DOE's ASC/ATDM program starting in 2015
- Goals:
 - Simulate plasmas over a broad density range, with Particle-In-Cell (PIC) dominating at low densities, fluid at high densities, and a hybrid approach in the middle.
 - Performance portability on next-generation architectures
- Code Design:
 - Three distinct physics capabilities that can be run stand-alone or coupled in a hybrid capability: Electromagnetics, PIC, Fluids
 - Built on top of many software components (Trilinos, Kokkos, Darma, ...)

3 The hybrid kinetic-fluid plasma model



Multiple algorithmic advances have been required for hybrid capability:

Fluid/Maxwell coupling enforces
divergence involution

Finite-element stabilization methods

> Fluid/particle collisions and merge

Step over stiff plasma modes using implicit/explicit time integration

Relativistic Klimontovich Equation

• Particles can collide: elastic, ionization, excitation etc.

$$\frac{\partial N_s(\boldsymbol{x}, \boldsymbol{u}, t)}{\partial t} + \boldsymbol{v} \cdot \nabla_x N_s + \frac{q_s}{m_s} \left(\mathbf{E} + \frac{\boldsymbol{v}}{c} \times \mathbf{B} \right) \cdot \nabla_u N_s = \left. \frac{\partial N_s(\boldsymbol{x}, \boldsymbol{u}, t)}{\partial t} \right|_c$$

$$egin{aligned} &
ho(oldsymbol{x},t) = \sum_{species} q_s \int doldsymbol{u} N_s(oldsymbol{x},oldsymbol{u},t) \ &oldsymbol{J}(oldsymbol{x},t) = \sum_{species} q_s \int doldsymbol{u} oldsymbol{u} N_s(oldsymbol{x},oldsymbol{u},t) \end{aligned}$$

Bettencourt et al, EMPIRE-PIC: A Performance Portable Unstructured Particle-in-Cell Code, Communications in Computational Physics, v30, 2021

Weight Particles

Maxwell's Equations

$$\nabla \cdot \boldsymbol{D}(\boldsymbol{x}, t) = \frac{\rho(\boldsymbol{x}, t)}{\epsilon_0}$$
$$\nabla \cdot \mathbf{B}(\boldsymbol{x}, t) = 0$$
$$\nabla \times \mathbf{E}(\boldsymbol{x}, t) = -\frac{\partial \mathbf{B}(\boldsymbol{x}, t)}{\partial t}$$
$$\nabla \times \boldsymbol{H}(\boldsymbol{x}, t) = \mu_0 \boldsymbol{J}(\boldsymbol{x}, t) + \mu_0 \epsilon_0 \frac{\partial \boldsymbol{D}(\boldsymbol{x}, t)}{\partial t}$$

Particles

5 Fluid Model: 5-Moment Multi-fluid Plasma

Density	$rac{\partial ho_a}{\partial t} + abla \cdot (ho_a \mathbf{u}_a) = \sum_{b eq a} (n_a ho_b ar{ u}_{ab}^+ - n_b ho_a ar{ u}_{ab}^-)$	
Momentum	$rac{\partial(ho_{a}\mathbf{u}_{a})}{\partial t} + abla \cdot (ho_{a}\mathbf{u}_{a}\otimes\mathbf{u}_{a} + p_{a}I + \Pi_{a}) = q_{a}n_{a}\left(\mathbf{E}+\mathbf{u}_{a} imes\mathbf{B} ight)$	$\rho_{\alpha}, \rho \mathbf{u}_{\alpha}, \varepsilon_{\alpha} \in H_{\nabla}(\Omega)$
	$-\sum_{b\neq a}\left[\rho_a(\mathbf{u}_a-\mathbf{u}_b)n_b\bar{\nu}^M_{ab}+\rho_b\mathbf{u}_bn_a\bar{\nu}^+_{ab}-\rho_a\mathbf{u}_an_b\bar{\nu}^{ab}\right]$	$p\alpha, p - \alpha, -\alpha v()$
Energy	$rac{\partialarepsilon_a}{\partial t} + abla \cdot ((arepsilon_a + p_a) \mathbf{u}_a + \Pi_a \cdot \mathbf{u}_a + \mathbf{h}_a) = q_a n_a \mathbf{u}_a \cdot \mathbf{E} + Q_a^{src}$	
	$-\sum_{b\neq a}\left[(T_a-T_b)k\bar{\nu}^E_{ab}-\rho_a\mathbf{u}_a\cdot(\mathbf{u}_a-\mathbf{u}_b)n_b\bar{\nu}^M_{ab}-n_a\bar{\nu}^+_{ab}\varepsilon_b+n_b\bar{\nu}^{ab}\varepsilon_a\right]$	
Charge and Current Density	$q = \sum_k q_k n_k \qquad \mathbf{J} = \sum_k q_k n_k \mathbf{u}_k$	
Maxwell's Equations	$rac{1}{c^2}rac{\partial {f E}}{\partial t}- abla imes {f B}+\mu_0 {f J}={f 0} \qquad abla \cdot {f E}=rac{q}{\epsilon_0}$	$\mathbf{E} \in \mathbf{H}_{\nabla \times}(\Omega)$
	$\frac{\partial \mathbf{B}}{\partial t} + \nabla \times \mathbf{E} = 0 \qquad \qquad \nabla \cdot \mathbf{B} = 0$	$\mathbf{B} \in \mathbf{H}_{ abla \cdot}(\Omega)$

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Target Problems



HERMES-III Background 7 ICTION CAVITIES

MARY INTERMEDIATE

EAS BRIDGE

DOG PROPERTY OF LO







Gamma ray simulator Nominally an 18MV, 550kA coaxial accelerator Uses Inductive Voltage Adders (IVAs) to combine Marx pulses Can operate in bremsstrahlung mode or an ion-diode mode (reverse polarization)

The HERMES III Pulsed Power Accelerator: MITL and courtyard







8

Self-consistent HERMES courtyard simulation

9



EMPIRE simulates the power flow in the Magnetically Insulated Transmission Line (MITL) and diode to generate the electrons incident on the vacuum side of the converter.

ITS simulates the radiation transport through the converter to generate the volumetric photon and electron plasma source for the courtyard simulation.



Contour DB: Ave_Mesh_courtyard.exo.72.0 Time:0 Var:rph@ton Density

1.0e+]

De+10

0e+09

VIOX: 0.0 Z

Min: 0.0

1.0e

-Axis

¹¹ Solution comparison between PIC and Hybrid



12 Saturn Accelerator

- A modular variable-spectrum X-ray source combining individual pulses from 36 individual modules to generate and convert ion/elec beams to intense X-ray output for component *testing* Electron beam: ~1.5 MeV, 8 10 MA, ~ 25 ns pulse
 X rays: 100 keV to 1.5 MeV
- SATURN is undergoing a refurbishment effort. EMPIRE simulations will advise new designs and experiments









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Note: waterline geometry not shown (no e- emission)



Trilinos Use



16 Trilinos Use in EMPIRE

• Directly uses 23 packages (enables 38 due to dependencies)

<u>Data Services</u> Teuchos Kokkos KokkosKernels Tpetra Zoltan2 Pamgen	<u>Discretizations</u> Shards Intrepid2 Phalanx Panzer SEACAS STK Percept	<u>Linear Solvers</u> Belos Anasazi Amesos2 Ifpack2 Stratimikos Teko MueLu	<u>Nonlinear</u> Sacado Thyra NOX
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EMPIRE-EM: ElectroMagnetic Solver

$$\begin{pmatrix} \Delta t^{-1} \mathbb{I}_{\mathcal{F}} & \mathbb{K}_{h} \\ -\mathbb{K}_{h}^{T} \mathbb{M}_{\mathcal{F}}(\mu^{-1}) & \Delta t^{-1} \mathbb{M}_{\mathcal{E}}(\epsilon) \end{pmatrix} \begin{pmatrix} \Delta \mathbf{B} \\ \Delta \mathbf{E} \end{pmatrix} = - \begin{pmatrix} \mathbf{r}_{\mathbf{B}} \\ \mathbf{r}_{\mathbf{E}} \end{pmatrix} \qquad \qquad \mathbf{B} \in \mathbf{H}_{\nabla}(\Omega) \\ \mathbf{E} \in \mathbf{H}_{\nabla \times}(\Omega)$$

Block LU Decomposition

$$\begin{pmatrix} \Delta t^{-1} \mathbb{I}_{\mathcal{F}} & \mathbb{K}_{h} \\ -\mathbb{K}_{h}^{T} \mathbb{M}_{\mathcal{F}}(\mu^{-1}) & \Delta t^{-1} \mathbb{M}_{\mathcal{E}}(\epsilon) \end{pmatrix} = \begin{pmatrix} \mathbb{I}_{\mathcal{F}} & 0 \\ -\Delta t \mathbb{K}^{T} \mathbb{M}(\mu^{-1}) & \mathbb{I}_{\mathcal{E}} \end{pmatrix} \begin{pmatrix} \Delta t^{-1} \mathbb{I}_{\mathcal{E}} & \mathbb{K}_{h} \\ 0 & \mathbb{S}_{\mathcal{E}} \end{pmatrix}$$

Assemble Schur Compliment as monolithic matrix

Solve for dE with PCG: Explicit back solve for dB:

$$\mathbb{S}_{\mathcal{E}} = \Delta t^{-1} \mathbb{M}_{\mathcal{E}}(\epsilon) + \Delta t \mathbb{K}_h^1 \mathbb{M}(\mu^{-1}) \mathbb{K}_h$$

$$S_{\mathcal{E}}\Delta \mathbf{E} = -\mathbf{r}_{\mathbf{E}} + \Delta t \mathbb{K}_{h}^{T} \mathbb{M}(\mu^{-1}) \mathbf{r}_{\mathbf{B}}$$
$$\Delta \mathbf{B} = -\Delta t \mathbb{K}_{h} \Delta \mathbf{E} - \Delta t \mathbf{r}_{\mathbf{B}}$$

Meshing: STK, Percept, SEACAS, Panzer Data Structures: Kokkos, KokkosKernels, Tpetra Assembly: Shards, Intrepid2, Panzer, Thyra

Linear Solve:

- Uses RefMaxwell AMG with Conjugate Gradient
- Chebyshev smoother
- Prec setup done once
- Belos, Teko, MueLu,
 Ifpack2, Amesos2,
 KokkosKernels, Zoltan2

Bettencourt, et. al., EMPIRE-PIC: A Performance Portable Unstructured Particle-in-Cell Code, 2021 Lourenco Beirao de Veiga, Konstantin Lipnikov, and Marco Manzini, Mimetic Finite Difference Method for Elliptic Problems. Bochev et al., An algebraic multigrid approach based on a compatible gauge reformulation of Maxwell's equations, 2008.

18 Scalability Tests

Simple Cavity

- Simplified physics in similar configuration to B-dot experimental geometry.
- Preloaded particles.
- Run for nominal 100 timesteps to gather metrics.



Generic Cavity

- Complex geometry.
- Preloaded particles for scaling studies.
- Run for nominal 100 timesteps for scaling studies.

Mesh	Elements	Nodes	Edges	Particles
RO	337k	60.4k	406k	16M
R1	2.68M	462k	3.18M	128M
R2	20.7M	3.51M	24.4M	1.0B
R3	166M	27.9M	195M	8.2B
R4	1.33B	223M	1.56B	66B

Mesh	Elements	Nodes	Edges	Particles*
RO	3.7M	660k	4.4M	360M
R1	25M	4.4M	30M	2.4B
R2	200M	32M	240M	19B
R3	1.6B	270M	1.9B	160B





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Machine	Nodes	Processor	Accelerator
Trinity (Haswell)	9436	2 × Intel Xeon E5-2698v3	-
Trinity (KNL)	9984	1 × Intel Xeon Phi 7250	-
Astra	2592	2 × Cavium Thunder-X2 CN9975	-
Sierra	4340	$2 \times IBM$ POWER9 22C	$4 \times NVIDIA V100$

ATS-2 performance improvements (simple cavity reference problem)



Particle update showed strong scaling issues

December 2019 results

August 2020 results



20

²¹ Performance results for the Generic Cavity



²² Performance results for the Generic Cavity

Cross-platform strong scaling results





²³ GC performance comparison to the legacy code



24 EMPIRE-PIC Optimized Data Structures

EMPIRE particle update is drastically faster than legacy code despite using the same algorithmOptimized data structures improve single node performance

Data models are critical

• AoS and SoA used to be the question people would argue over - EMPIRE uses SoSoAoS

SoSoAoS - ParticleContainer core structure (holds Kokkos::DynamicView of data)

- Enables constant time insertion
- Enables continuous memory access
- $\circ\,$ Allows code to access just one variable at a time (position, velocity, $\dots\,)$

Particles are marked for deletion and then removed later

• Contiguous memory access for better performance

Atomic operations are available for parallel lock free addition and deletion of particles

Memory pools are used for all temporaries and recycled – allocations are slow





²⁶ Fluid/Hybrid Solver

- Discontinuous Galerkin
 - KokkosKernels to invert local mass matrices
- Assembly uses Sacado, Phalanx, Intrepid2, Panzer
 - Automatic Differentiation
- Fluid solver uses an IMEX RK scheme
- Optionally coupled to EMPIRE-EM and EMPIRE-PIC
 - Nonlinear iteration is accelerated using Anderson acceleration (NOX)



Explicit Hydrodynamics

Implicit EM, EM sources, sources for species interactions

27 Fluid/Hybrid Solver

- For an ideal Newton-based solve, we would couple with a Schur complement preconditioner.
- We instead choose the discretization and solution method to avoid a global solve of the fully coupled system
 - Nonlinear solve with Anderson acceleration
 - Discontinuous Galerkin (DG) for the Fluid equations
 - IMEX time integration with **explicit** hydrodynamics
- DG and explicit hydro
 - Decoupled local block diagonal matrices
 - Blocks are solved in parallel using KokkosKernels
 - Leverages fast Maxwell solver described earlier
- Global nonlinear solve uses Anderson acceleration
 - Solve a Quasi-Newton linear system in the Picard mapping: x = g(x)
 - Account for coupling via by adding a local approximation to the Lorentz force operator to the block diagonals.

$$J_k \Delta x_k = -f(x_k)$$
$$x_k = x_k + \Delta x_k$$





Fluid Linear Solve:

- Block diagonal solver
- KokkosKernels: KokkosBatched_LU and KokkosBatched_Trsm
- NOX

Hybrid Two Fluid Plasma Vortex Verification Problem

- Two fluid plasma vortex in MHD limit
- IMEX time discretization, DG fluid discretization, CG Maxwell discretization
- Using Schur-Complement in all simulations



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Dynamic task-based load balancing using DARMA

- PIC can spatially concentrate particles, causing load imbalance
- DARMA/vt (virtual transport): C++ asynchronous tasking runtime
- Includes suite of highly scalable, fully distributed load balancers
- Trilinos and Darma coexist, switching between bulk sync and tasking comm layers





PI: Jonathan Lifflander, Analyst: Brandon Medina

EMPIRE has demonstrated performance portability

Next steps regarding Trilinos co	Strong partnership with Irilinos Multiple embedded Irilinos developers on the tear	
Trilinos is heavily leveraged	Solvers and discretiza	ation tools critical to success
EMPIRE strong and weak scales	Iterative advances yie	elded significant improvements
EMPIRE runs on all target platform	ns Achieved with no plat	tform-dependent code