





Center for Computing Research



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Main collaborators:

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Trilinos User Group meeting, Albuquerque, Oct 2022

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² Talk Outline

- Brief motivation and introduction to ice sheet equations
- MALI ice sheet model description
- Recent developments
- Newly funded project FanSSIE and plan for next five years
- Deep dive into work for improving performance and portability

Supported by US DOE Office of Science projects:

- ProSPect: Probabilistic Sea-Level Projections from ice sheets and Earth System Models
- FASTMath: Frameworks, Algorithms and Scalable Technologies for Mathematics
- > E3SM: Energy Exascale Earth System Model
- FANSSIE: Framework for Antarctic System Science In E3SM

Why is it important to model ice sheets? (sea level rise in the last three decades)



Contributors to global sea level rise (1993-2018):



Simulation of Antarctic ice sheet as a consequence of extreme (unrealistic) climate forcing that induces collapse of ice shelves

Goal: probabilistic projections of sea level rise (projections of future sea level rise)

(feet) levels intermediate-high 2000 ntermediate height abov observed trend intermediate-low low 2020 2040 2000 2060 2080 2100 year NOAA Climate.gov, adapted from Sweet et al., 2022

Note: regional sea-level rise can significantly exceed the global mean sea level rise in some areas (e.g. in the Gulf of Mexico).

Simulation of Antarctic ice sheet as a consequence of extreme (unrealistic) climate forcing that induces collapse of ice shelves



Possible pathways for future sea-level rise

(h

Ice speed (m yr

Brief Motivation on basic physics

- Modeling ice sheets (Greenland and Antarctica) dynamics is <u>essential to provide estimates for sea-</u> <u>level rise in next decades to centuries.</u>
- Ice behaves like a <u>very viscous shear-thinning fluid</u> (similar to lava flow) driven by gravity.
- An essential step in ice sheet modeling is to estimate the unknown or poorly known parameters (e.g. basal friction, bed topography) and the initial thermomechanical state of the ice *Initialization*
- It is critical to determine how uncertainties in the data and the model affect projections of sealevel rise.





Model: Ice velocity equations

Stokes equations:

 $\begin{cases} -\nabla \cdot \sigma = \rho \mathbf{g} \\ \nabla \cdot \mathbf{u} = 0 \qquad \text{gravit. acceleration} \\ & & \text{ice velocity} \end{cases}$

Stress tensor: $\sigma = 2\mu \mathbf{D} - pI, \quad \mathbf{D}_{ij}(\mathbf{u}) = \frac{1}{2} \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right)$ Ice viscosity (dependent on temperature): $\mu = \frac{1}{2} A(T) |\mathbf{D}(\mathbf{u})|^{\frac{1}{n}-1}, \quad n \ge 1$

Sliding boundary condition at ice bed:

 $\begin{cases} \mathbf{u} \cdot \mathbf{n} = 0, & \text{(impenetrablity)} \\ (\sigma \mathbf{n})_{\parallel} = \beta \mathbf{u} \end{cases}$

Free slip:
$$\beta = 0$$
No slip: $\beta = \infty$



Note: We use a simplification of Stokes equations, called First-Order (FO) model, derived exploiting the shallow nature of the ice sheets and using hydrostatic pressure.

7 Model: Temperature equation

Heat equation (for cold ice):

Boundary condition at the <u>ice bed</u> (includes melting and refreezing):



frictional
heating

$$\mathbf{m} = \mathbf{G} + \beta |\mathbf{u}|^2 - k \nabla T \cdot \mathbf{n}$$

$$\mathbf{M} = \mathbf{G} + \beta |\mathbf{u}|^2 - k \nabla T \cdot \mathbf{n}$$
temperature
melting geothermal flux
heat flux

In this work we use a enthalpy formulation* that accounts for temperate ice as well.

*A. Aschwanden, E. Bueler, C. Khroulev, and H. Blatter, Journal of Glaciology, 2012

Software: MPAS-Albany Land Ice model (MALI)

ALGORITHM	SOFTWARE TOOLS	
Linear Finite Elements on tets/prisms	Albany Land Ice	
Optimization	ROL	
Nonlinear solver (Newton method)	NOX	
Krylov linear solvers/Prec	Belos/MueLu, Belos/FROSch	dise
Automatic differentiation	Sacado	
Mesh structure	SEACAS /STK	



MPAS (Model for Prediction Across Scales): *Fortran*, **finite volumes** library, conservative Lagrangian schemes for advecting tracers (evolution of ice thickness), coupling to E3SM

Albany Land Ice: *C*++ finite element library built on top of **Trilinos** achieving performance portability through **Kokkos** programming model. Provides large scale PDE constrained optimization capabilities

Note: MPAS land-ice layer to be removed in the future. Albany will be coupled directly to E3SM

References:

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Hoffman, et al. GMD, 2018 Tuminaro, Perego, Tezaur, Salinger, Price, SISC, 2016. Tezaur, Perego, Salinger, Tuminaro, Price, Hoffman, GMD, 2015 Perego, Price, Stadler, JGR, 2014



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Recent development: (code development)

- Improvements to solvers portability and performance monitoring (see Jerry's deep dive)
- Hessian AD Piro/ROL/Sacado
 - Matrix-free second-order derivatives of residual and responses w.r.t. solution and distributed parameters
 - > Assembly of Hessian matrix of scalar response using coloring and seeding (Zoltan2)
 - Enables second-order (e.g. Trust Region) optimization methods
- **PyAlbany** (see related PyTrilinos talk tomorrow by K. Liegeois)
 - Python interface to Albany based on pybind11.
 - > Drives Albany forward solves and analysis solves and allows fast and easy prototyping and postprocessing
 - ➢ Used for parameter tuning of solvers, running inverse problems and ensembles for UQ analysis





300K parameters, 14M unknowns. Initialization: ~10 hours on 2k nodes on NERSC Cori (Haswell), The optimization is constrained by the **coupled velocity-temperature** solvers. Most large scale-ice sheets codes constrain the optimization only with the velocity solver, which results in a temperature field that is not consistent with the velocity

Framework for Antarctic System Science in E3SM (Recently funded Office of Science BER SciDAC 5-years project)

Project main goals:

- improve modeling of physical processes (ice calving, fracture, ocean coupling, surface processes) that can significantly impact the contribution of Antarctic ice sheet to sea-level change
- provide uncertainty quantification of sea level projections
- Improvements to model to support science and run efficiently on DOE machines

Project team:

LANL (lead institute, PI: Matt Hoffman) Sandia (M. Perego, L. Bertagna, M. Carlson, J. Hu, K. Liegeois, I. Tezaur, J. Watkins) LBNL (POC: S. Williams) BNL (POC: N. Urban) UM (J. Bassis) RPI (M. Shephard) UCI (C. Zehnder)



12 Plan for next 5 years: (code development)

- Improvements to performance and portability (see Jerry's deep dive)
- Mesh Adaptation (collaboration w/ RPI)
 - Use Omega_h mesh
 - Align mesh with important ice features (calving front, grounding line, rifts)
 - Add level-set equations for capturing ice front and rifts (possibly use Krino)

• High-order discretization

- Exploit tensor-product structure of extruded mesh PanzerDofMgr/Intrepid2
- Transient PDE-Constrained Optimization Piro/ROL/Tempus/Sacado



¹³ **Performance Highlights**

- Major improvements to finite element assembly time
 - Memoization to avoid unnecessary data movement and computation
 - Tpetra::FECrsMatrix refactor to reduce memory footprint and data movement
 - Boundary condition refactor to reduce memory footprint and data movement
- Solver portability on Cori and Summit
 - MueLu SemiCoarsen refactor using Kokkos
 - Ifpack2 portable smoothers tuned to GPU hardware
- Automated performance testing
 - Changepoint detection for performance monitoring

Watkins, J., Carlson, M., Shan, K., Tezaur, I., Perego, M., Bertagna, L., Kao, C. *et al.* "Performance portable ice-sheet modeling with MALI." (Submitted to IJHPCA, 2022) <u>https://arxiv.org/abs/2204.04321</u>





Performance on Cori and Summit

- Setup
 - Weak scalability First-order Stokes, Antarctica 1km resolution, up to 256 nodes
 - Different smoothers CPU block smoother, GPU point smoother

• Results

- CPU scales better than GPU 65% (CPU) vs. 42% (GPU)
- Speedup on GPU 1.9-1.2x speedup over CPU
- Areas to improve
 - ➤ Assembly on CPU 40-60% of total time
 - Solver on GPU 80-90% of total time



Detecting performance regressions/improvements

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Example: Transition to Kokkos 3.5.0 caused a performance regression but was soon fixed



Total Fill time for a 1-to-7 km resolution Greenland mesh, executed nightly in Albany Land Ice

Improvement

Monitoring performance comparisons

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Example: Memoization comparison (w. & w.o.) shows that relative performance has increased



Speedup of Total Fill time from memoization for a 1-to-7 km resolution Greenland mesh, executed nightly in Albany Land Ice

Automatic performance tuning

Example: Autotuning used to improve performance of multigrid smoothers on GPU



Best runtimes for a range of function evaluation budgets – 3-to-20 km resolution Greenland mesh **Best runtimes** using GPTune Bayesian optimization, Latin Hypercube Sampling and Monte Carlo Sampling – 3-to-20 km resolution Greenland mesh

Carlson, M., Watkins, J., Tezaur, I. "Automatic performance tuning for MPAS-Albany Land Ice." (Submitted to JCAM, 2022)

¹⁸ Future Performance Overview



Algorithmic improvements and performance optimization

• Team members

- SNL: Luca Bertagna, Max Carlson, Jonathan Hu, Kim Liegeois, Mauro Perego, Irina Tezaur, Jerry Watkins
- LBNL: Oscar Antepara, Sam Williams
- Algorithmic improvements
 - ➢ Improved convergence of linear solver on GPUs (FY24)
 - Block fine grid smoother
 - Physics-based block preconditioning for coupled problems (FY25)
- Performance optimization
 - Unified Virtual Memory (UVM) optional (FY23)
 - Optimize multigrid solvers for 2D advection-diffusion (FY25)
 - Evaluate/improve performance of initialization (optimization problem) (FY25)
 - ▶ Investigate load balancing and frequency of mesh adaptation (FY26)
 - Optimize data movement in MALI & Omega_h coupling (FY26)
 - Evaluate portability to DOE Exascale (Frontier/Aurora) (FY27)